

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization
International Bureau



(43) International Publication Date
15 November 2001 (15.11.2001)

(10) International Publication Number
WO 01/85262 A1

(51) International Patent Classification²: A63B 5/11 (81) Designated States (national): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, TZ, UA, UG, US, UZ, VN, YU, ZA, ZW.

(21) International Application Number: PCT/KR01/00635 (84) Designated States (regional): ARIPO patent (GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TI, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE, TR), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG).

(22) International Filing Date: 17 April 2001 (17.04.2001)

(25) Filing Language: Korean

(26) Publication Language: English

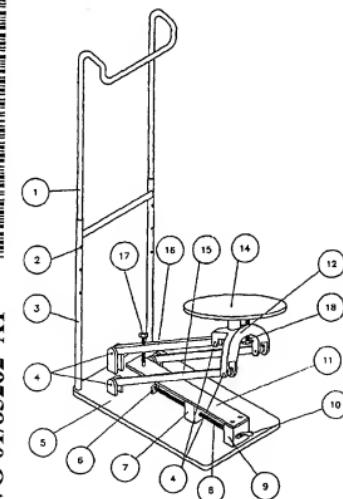
(30) Priority Data: 2000-22306 24 April 2000 (24.04.2000) KR

(71) Applicants and
(72) Inventors: OH, Kyoung-Chan [KR/KR]; Apt. 545-1,2Gn, 2-805, Geosung-green, Jungwhasan-Dong, Wansan-Ku, Jeonju-City 560-250 (KR). OH, Ju-Whan [KR/KR]; Apt. 545-1,2Gn, 2-805, Geosung-green, Jungwhasan-Dong, Wansan-Ku, Jeonju-City 560-250 (KR).

Published:
— with International search report

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

(54) Title: ELASTICITY-CONTROLLABLE TRAMPOLINE USING PLATE SPRING



(57) Abstract: Disclosed is an elasticity-controllable trampoline using a plate spring that can be manufactured in small size and in low height compared with existing trampolines using coil springs, thereby proving stability to a user. Also, it has a mechanical structure, thereby providing a semi-permanent life term. Under the principles of a lever using the third law of motion, particularly, the plate spring carries out action in smooth manner, in operation and also carries out reaction with the jumping operation of the user, such that the trampoline of the present invention will have strong elasticity. In addition, a plate spring support movable stand on the plate spring is moved in simple manner according to the principles of the lever, thereby allowing the elasticity of the plate spring to be controlled. With the adjustment of the upward and downward motion of an action point operation bolt, the height of the upward and downward motion can be adjusted. Specifically, the step plate is maintained at a horizontal state upon upward and downward motion, by the adoption of a coupling movable member for maintaining the step plate horizontally, and a bearing sheet is formed on the step plate with a result that the step plate can carry out a twist motion.

WO 01/85262 A1

ELASTICITY-CONTROLLABLE TRAMPOLINE USING PLATE SPRINGTechnical Field

5 The present invention relates to an elasticity-controllable trampoline using a plate spring.

Background Art

10 A conventionally developed trampoline operates in such a manner that a plurality of coil springs are coupled to an iron frame, so that it occupies a relatively large area. Moreover, the trampoline can control the elasticity thereof only with the attachment and detachment of the coil springs. The trampoline is formed by fabrics, thereby making it difficult for a user to maintain a horizontal level, and it is
15 also difficult to install a handle grip thereon in terms of the characteristics of the trampoline, thereby not providing any stability to the user. In addition, serious noises are caused at the time of friction between the plurality of coil springs. Because of these problems, there is a need for a novel small-sized trampoline capable of providing stability and convenience to the user.

20

Disclosure of Invention

It is an object of the present invention to provide an elasticity-controllable trampoline, using a plate spring adopting lever principles, in which upon action it
25 operates by the lever principles and upon reaction it exerts an elastic force at a time, under the law of action and reaction as third law of motion, whereby the trampoline produces a strong elastic force at an expense of small force, has a relatively low height relative to an operation distance, provides a step plate that is level with the surface of land, thereby permitting the stability of use, occupies a relatively small

area, controls the available elasticity if necessary, adjusts the motion height (the operation distance) if necessary and does not produce any noise, such that it can be effective as indoor sporting goods, manufactured at a low production cost and semi-permanently used for a long period of time.

5 To accomplish the above objects of the present invention, there is provided an elasticity-controllable trampoline using a plate spring, which includes: a fixed plate and a step plate coupled by means of a knuckle pin on the both sides of a step plate coupling movable member and a coupling movable member for maintaining the step plate horizontally; the plate spring operated by means of an action point
10 operation bolt; and a plate spring support movable stand moved by the rotation of a horizontal moving shaft with a thread for moving the plate spring support movable stand, whereby the elasticity of the plate spring can be controlled and upward and downward motion distance can be controlled under a length control by means of the action point operation bolt.

15

Brief Description of the Drawings

Further objects and advantages of the invention can be more fully understood from the following detailed description taken in conjunction with the
20 accompanying drawings, in which:

FIG. 1 is a perspective view of an elasticity-controllable trampoline using a plate spring according to an embodiment of the present invention;

FIG. 2 is a sectional view of the elasticity-controllable trampoline of the present invention; and

25 FIGS. 3 to 5 are sectional views of the elasticity-controllable trampoline according to another embodiments of the present invention.

Best mode for Carrying Out the Invention

According to the present invention, as shown in FIGS. 1 and 2 an elasticity-controllable trampoline using a plate spring is constructed in such a manner that a step plate 14 is coupled on the upper end of a fixed plate 5 with a step plate coupling movable member 16 and a coupling movable member 15 for maintaining 5 the step plate 14 horizontally via a knuckle pin 4, with a result that the step plate 14 can be operated upward and downward. Thus, the step plate 14 operates at the expense of small force by virtue of an action point operation bolt 17 under the principles of a lever. Moreover, the plate spring 11 adopts the principles of the lever in accordance with the movement of a plate spring support movable stand 7. 10 As a result, the principles of the lever are embodied twice in the elasticity-controllable trampoline according to the present invention. Thereby, the trampoline of the present invention operates under the third law of motion.

The plate spring 11 is secured at the one side thereof by virtue of a holder 9 for a horizontally moving shaft 8 and operates upward and downward, based upon 15 the operation force of the action point operation bolt 17. And, the plate spring support movable stand 7 moves on the thread of the horizontally moving shaft 8, thereby providing an effect of moving the support point of the lever. Therefore, a degree of action of force is varied in proportional to the operation distance, such that the elastic force the plate spring 11 has can be controlled. The upward and 20 downward motion distance is adjusted by the rotation of the action point operation bolt 17, such that the upward and downward motion distance of the step plate 14 can be controlled. In order to eliminate friction around the pin of the action point operation bolt 17, a ball bearing is inserted into the action point operation bolt 17. The coupling movable member 15 for maintaining the step plate 14 horizontally 25 can operate in horizontal relation with the step plate 14 by virtue of the movable member and the knuckle pin 4 on the step plate 14 and the fixed plate 5.

Under the aforementioned construction, an explanation of the operation and effect of the trampoline of the present invention will be below discussed. A rotary handle grip 10, which is coupled to the horizontal moving shaft 8 with the thread

for moving the stand 7, rotates left and right, with a result that the plate spring support movable stand 7 is positioned at a predetermined location, thereby permitting the elastic force available to be determined. As the action point operation bolt 17 rotates left and right, it is adjusted in length, so that the height of
5 the motion is controlled. Under the above state, if a user gets and stamps on the step plate 14, the force is applied to the step plate coupling movable member 16 coupled to the step plate 14, with a consequence that the action point operation bolt 17 makes the plate spring 11 descended. When the operation elasticity reaches a
10 limit, the step plate 14 is ascended by the action of a strong restoring force of the plate spring 11, with a result that the user can be elastically jumped. At this time, the principles of the lever adopted repeatedly by the location of the plate spring support movable stand 7 and the operation position of the action point operation bolt 17 are employed with the elasticity of the plate spring 11 in mixed relation to each other, so that a substantially strong elastic force from the plate spring 11 can
15 be exhibited at the expense of small force. Also, the rotation of the step plate 14 is made by virtue of a bearing sheet that is disposed on a step plate fixing member
12.

Referring to FIG. 3 showing the elasticity-controllable trampoline using the plate spring according to another embodiment of the present invention, only the
20 step plate coupling movable member 16 is coupled on the fixed plate 5 by means of the knuckle pin 4, and the step plate coupling movable member 16 is integrally coupled with the step plate 14 on the other side thereof.

Referring to FIGS. 4 and 5 showing the elasticity-controllable trampoline using the plate spring according to yet another embodiments of the present
25 invention, a roller 20 is coupled on a plane plate 19, and the action point operation bolt 17, which is integrally formed with the step plate coupling movable member 16, operates on the plane plate 19 such that the elastic force of the plate spring 11 and the operation of the step plate 14 become smooth.

Industrial Applicability

As set forth in the foregoing, an elasticity-controllable trampoline using a plate spring according to the preferred embodiments of the present invention 5 operates by double adoption of the principles of a lever and utilizes the elastic force of the plate spring, whereby it exhibits an excellent elasticity, thereby providing a strong jumping force to a user at the time of operation. In addition, the trampoline of the present invention can control the elasticity thereof and the width of upward and downward motion. Moreover, it can maintain a step plate at a horizontal state 10 upon upward and downward motion, and the height of the step plate is substantially low when compared with the operation distance, thereby providing stability to the user. Also, it is manufactured in small size such that it is easy to move, and it is also manufactured at a low production cost such that it has competition in price. Based upon the above, it can be appreciated that the trampoline of the present 15 invention will be the indoor sporting goods having an excellent effect.

What Is Claimed Is:

1. An elasticity-controllable trampoline using a plate spring, comprising:
 - 5 a fixed plate and a step plate coupled by means of a knuckle pin on the both sides of a step plate coupling movable member and a coupling movable member for maintaining said step plate horizontally;
 - 10 said plate spring operated by means of an action point operation bolt; and a plate spring support movable stand moved by the rotation of a horizontal moving shaft with a thread for moving said plate spring support movable stand, whereby the elasticity of said plate spring can be controlled and upward and downward motion distance can be controlled under a length control by means of said action point operation bolt.
- 15 2. The trampoline as defined in claim 1, wherein only said step plate coupling movable member is coupled on said fixed plate by means of said knuckle pin, and said step plate coupling movable member is integrally coupled with said step plate on the other side thereof.
- 20 3. The trampoline as defined in claims 1 to 2, wherein said action point operation bolt, which is integrally formed with said step plate coupling movable member, operates on a plane plate to which a roller is coupled, such that the elastic force of said plate spring and the operation of said step plate become smooth.

[Drawings]

FIG. 1

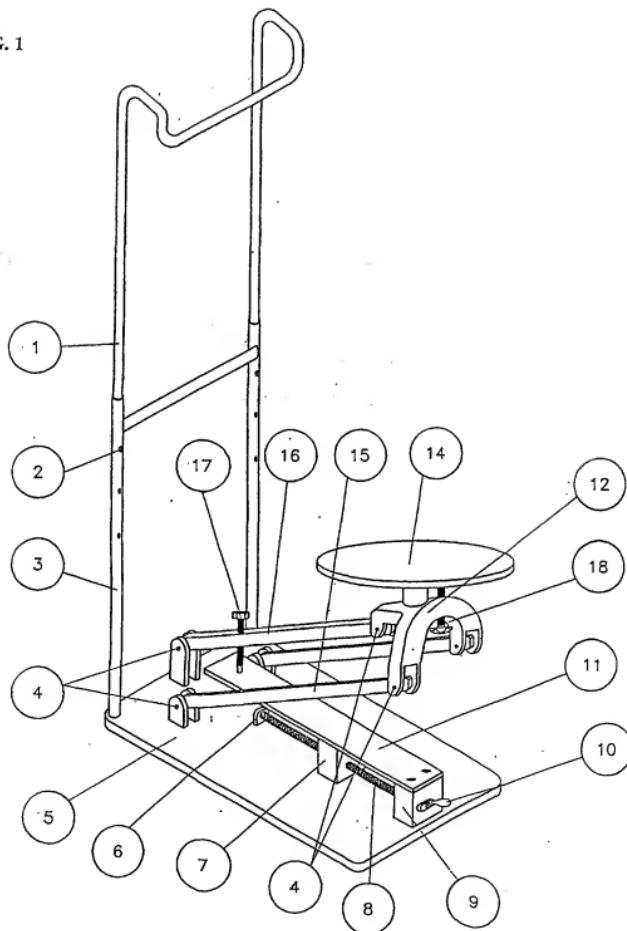


FIG. 2

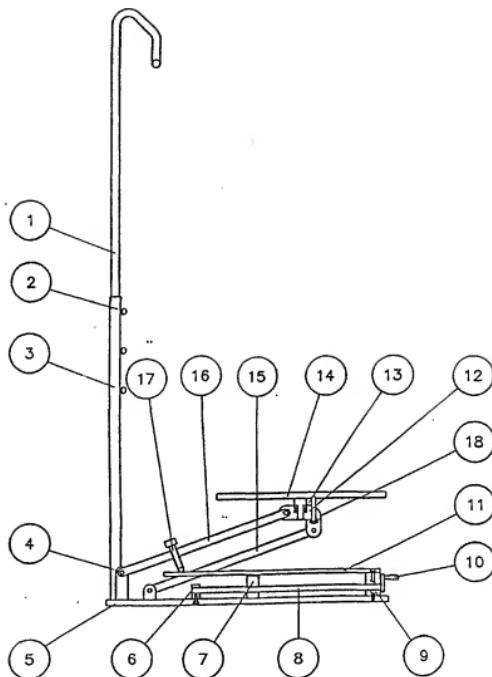


FIG. 3

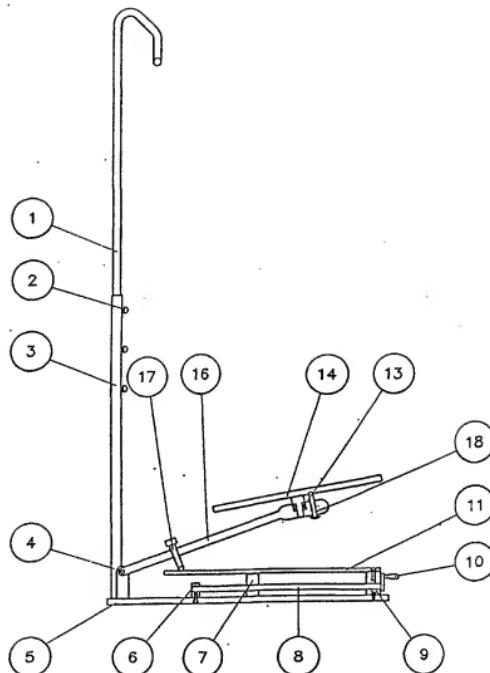
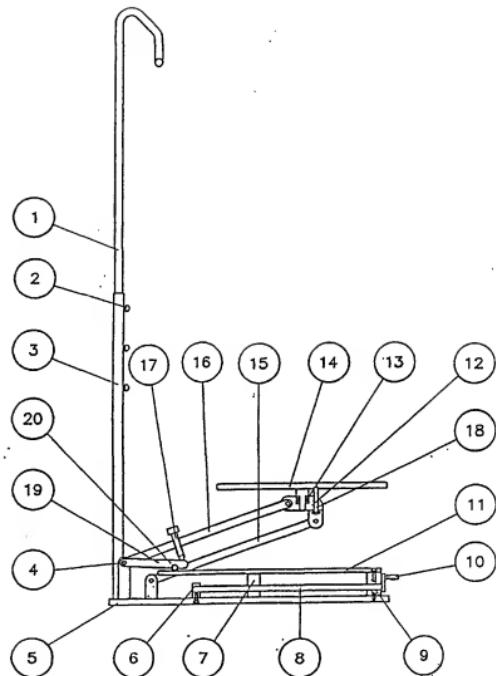
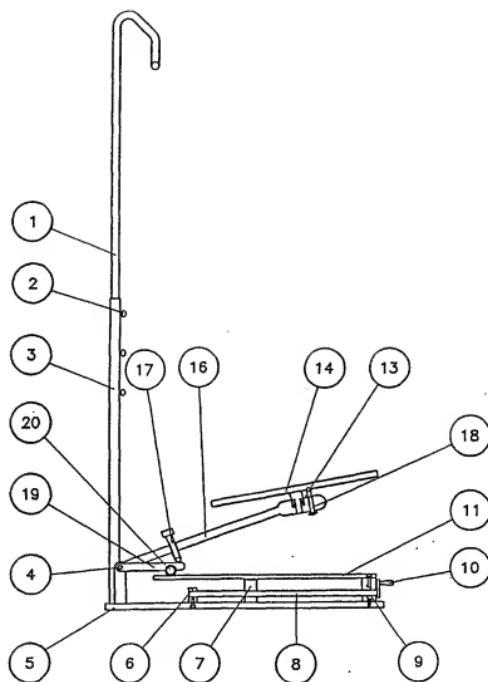


FIG. 4



5/5

FIG. 5



INTERNATIONAL SEARCH REPORT

International application No.
PCT/KR01/00635

A. CLASSIFICATION OF SUBJECT MATTER		
IPC7 A63B 5/11		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED		
Minimum documentation searched (classification system followed by classification symbols)		
IPC7 A63B 5/11		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched		
Korean Patents and applications for inventions since 1975		
Korean or Japanese Utility models and applications for Utility models since 1975		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 4645197 A (Richard McFee) Feb. 24, 1987 Abstract and Fig.2	1
A	US 4341380 A (Walter J. Sauder) Jul. 27, 1982 Abstract and Fig.1	1
A	US 4477070 A (Jog-et, Inc.) Oct. 16, 1984 Abstract and Fig.1	1
A	KR 93-21105 U (Soonhak, PARK) Oct. 15, 1993 Abstract and Fig.1	1
<input type="checkbox"/> Further documents are listed in the continuation of Box C. <input type="checkbox"/> See patent family annex.		
<p>* Special categories of cited documents:</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier application or patent but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone</p> <p>"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art</p> <p>"&" document member of the same patent family</p>		
Date of the actual completion of the international search	Date of mailing of the international search report	
25 AUGUST 2001 (25.08.2001)	27 AUGUST 2001 (27.08.2001)	
Name and mailing address of the ISA/KR Korean Intellectual Property Office Government Complex-Daejeon, Dunsun-dong, Seo-gu, Daejeon Metropolitan City 302-701, Republic of Korea Faximile No. 82-42-472-7140	Authorized officer YANG, Jong Pil Telephone No. 82-42-481-5450	
		